

Recurrent Neural Networks

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References:

- *Hands-On Machine Learning with Scikit-Learn, Keras and TensorFlow* by Aurélien Géron (O'Reilly). 2019, 978-1-492-03264-9.
- François Chollet, *Deep Learning with Python*, Manning Pub. 2018

Outline

1. Introduction
2. Recurrent neurons and layers
3. Training RNNs
4. Forecasting a time series
 1. Implementing a simple RNN
 2. Deep RNNs
 3. Forecasting Several Time Steps Ahead
5. Handling long sequences
 1. LSTM cell
 2. GRU cell
6. Exercises

Introduction

- YouTube Video: *Deep Learning with Tensorflow - The Recurrent Neural Network Model* from Cognitive Class

<https://youtu.be/C0xoB8L8ms0>

1. Introduction

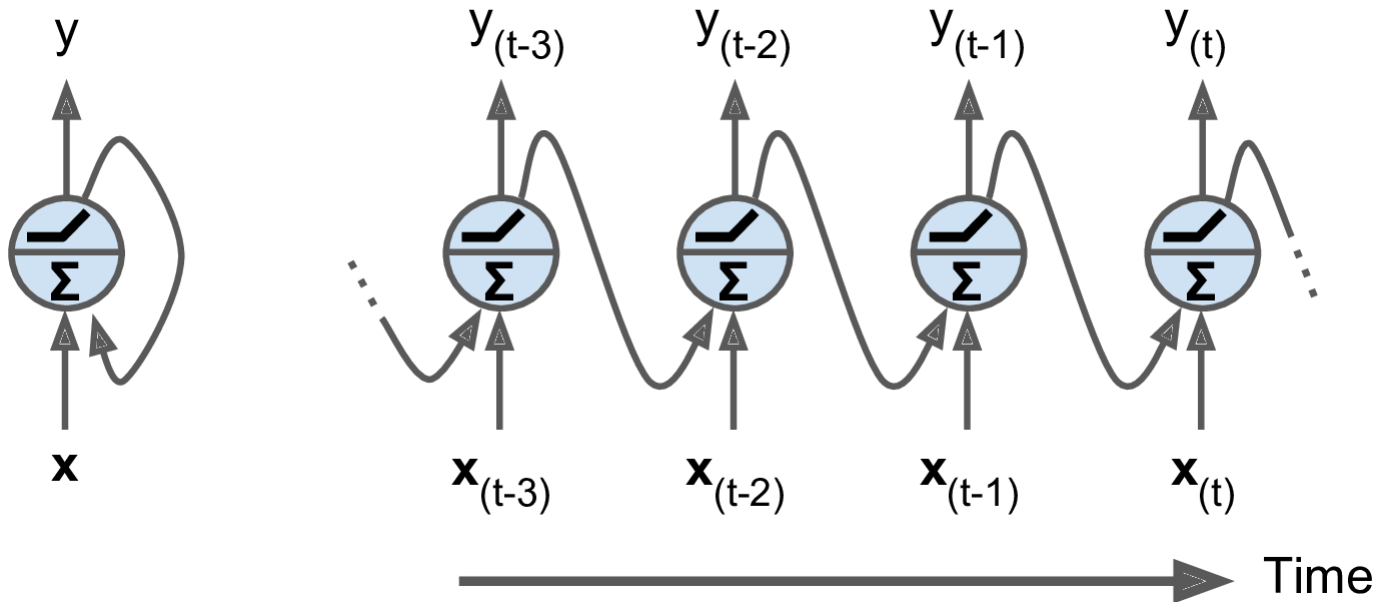
- **Recurrent neural networks (RNNs)** are used to handle time series data or sequences.
- Applications:
 - Predicting the future (stock prices)
 - Autonomous driving systems (predicting trajectories)
 - Natural language processing (automatic translation, speech-to-text, or sentiment analysis)
 - Creativity (music composition, handwriting, drawing)
 - Image analysis (image captions)

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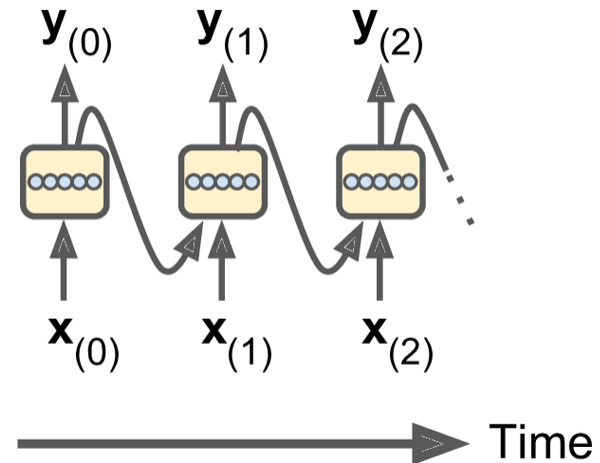
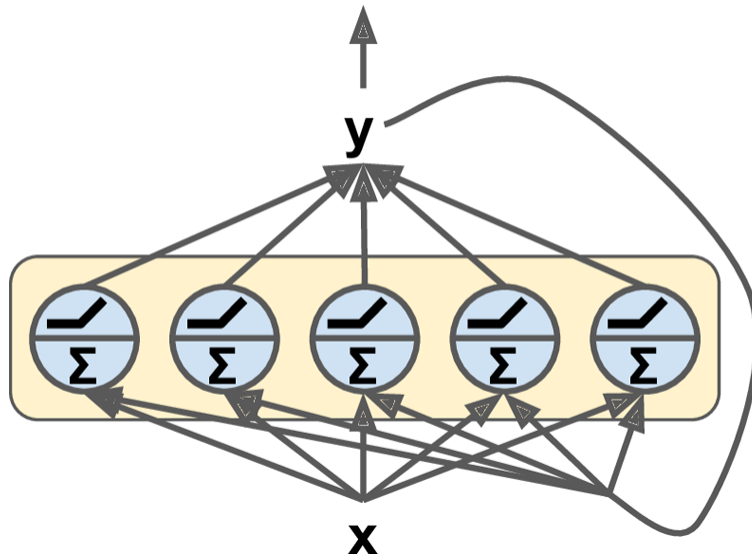
2. Recurrent Neurons and Layers

- The figure below shows a **recurrent neuron** (left), unrolled through time (right).



2. Recurrent Neurons and Layers

- Multiple recurrent neurons can be used in a **layer**.

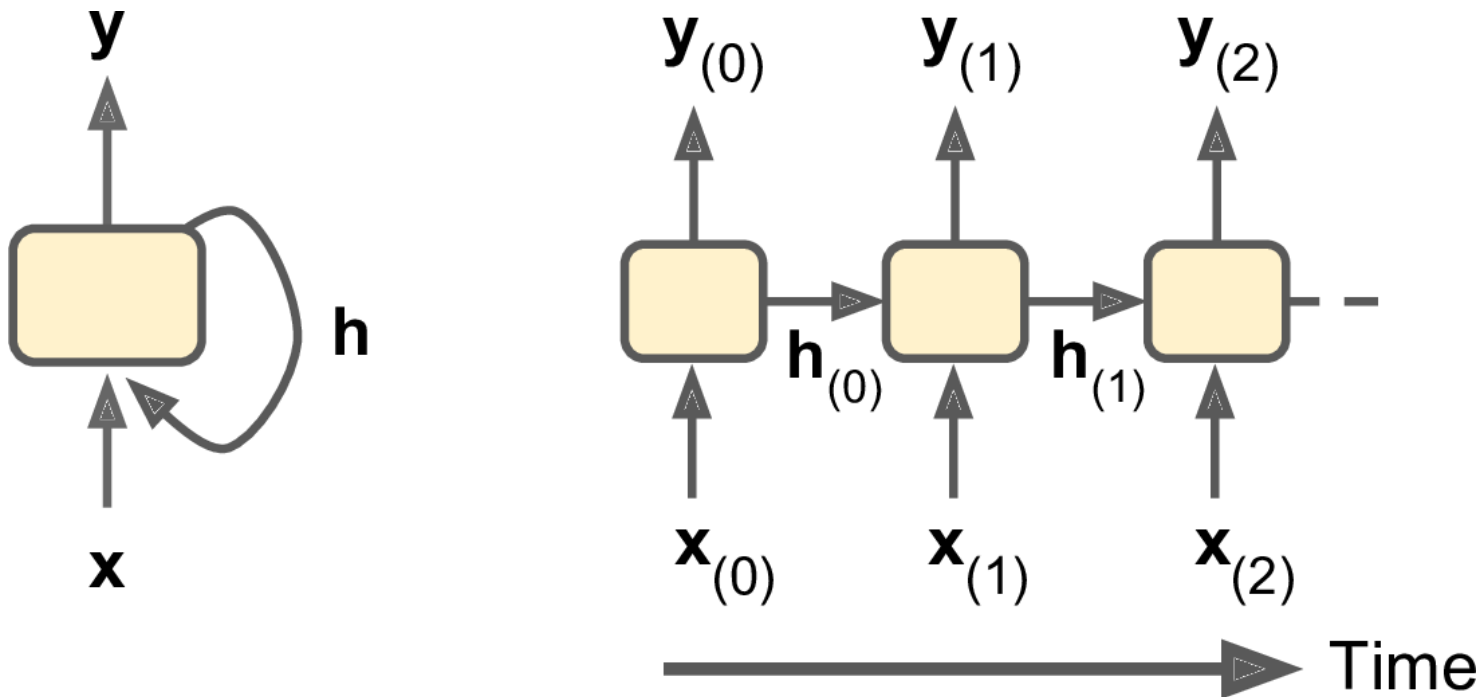


- The **output** of the layer is:

$$\mathbf{Y}_{(t)} = \phi(\mathbf{X}_{(t)} \cdot \mathbf{W}_x + \mathbf{Y}_{(t-1)} \cdot \mathbf{W}_y + \mathbf{b})$$

2. Recurrent Neurons and Layers

- Recurrent neurons have memory (hold state) and are called **memory cells**.
- The state $\mathbf{h}_{(t)} = f(\mathbf{h}_{(t-1)}, \mathbf{x}_{(t)})$, not always $\equiv \mathbf{y}_{(t)}$



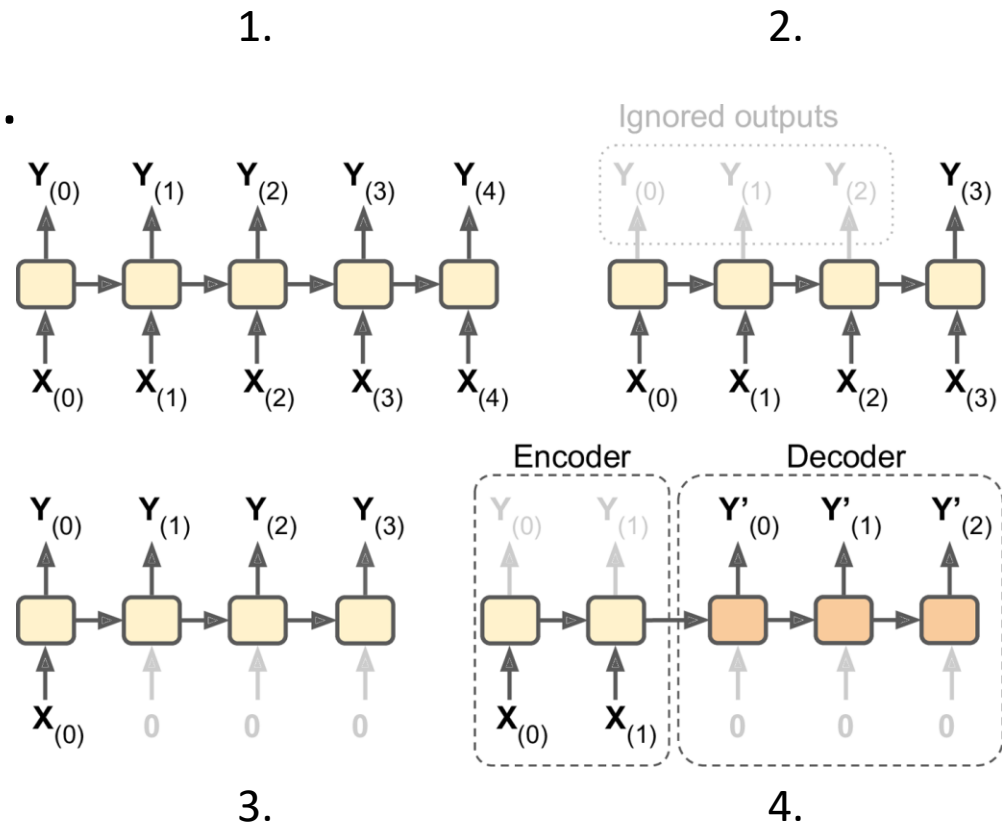
2. Recurrent Neurons and Layers: Input and Output Sequences

1. **Seq to seq net.:** For predicting the future.

2. **Seq to vector:** For analysis, e.g., sentiment score.

3. **Vector to seq:** For image captioning.

4. **Encoder-decoder:** For sequence transcription.

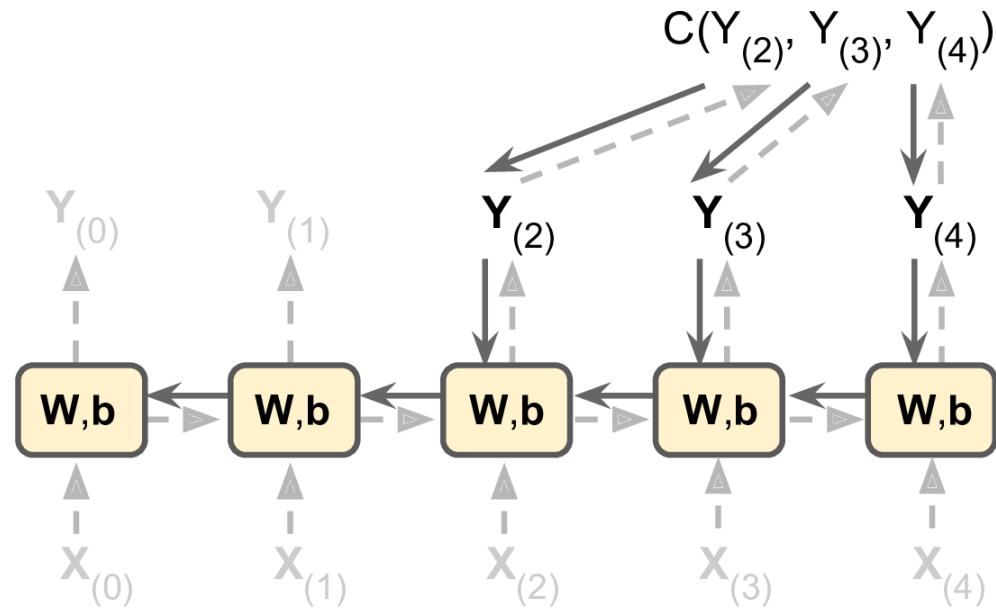


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3. Training RNNs

- Training using strategy called **backpropagation through time** (BPTT).
- Forward pass (dashed)
- Cost function of the not-ignored outputs.
- Cost gradients are propagated backward through the unrolled network.

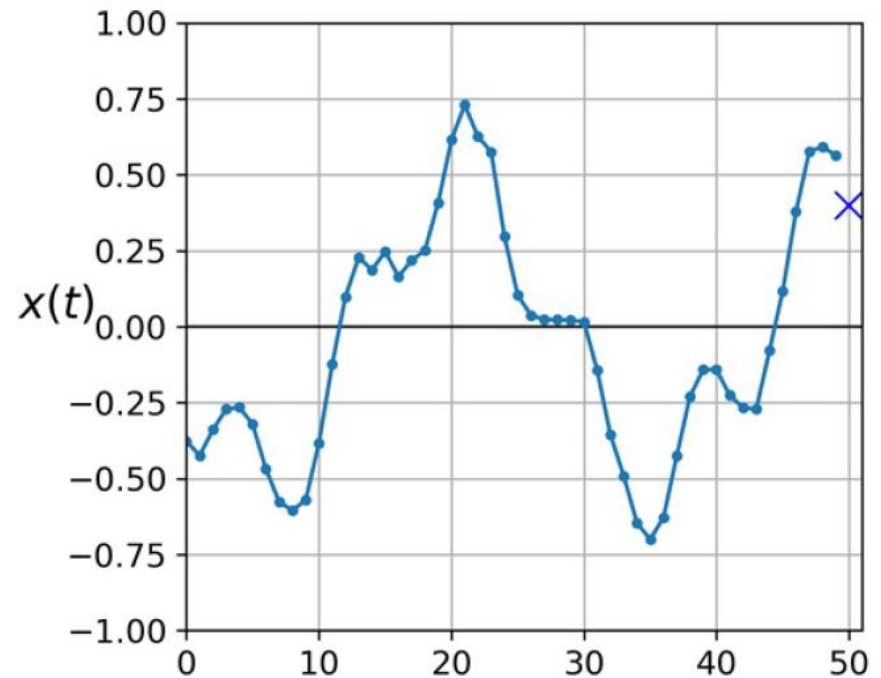


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4. Forecasting a Time Series

- The data is a sequence of one or more values per **time step**.
 - **Univariate** time series
 - **Multivariate** time series
- **Forecasting**: predicting future values
 - Forecast the next value
 - Forecast N next values



4.1 Implementing a Simple RNN

```
# Generate 10,000 time series
n_steps = 50
series = generate_time_series(10000, n_steps + 1)

# Split them 7,000 : 2,000 : 1,000
X_train, y_train = series[:7000, :n_steps],
                    series[:7000, -1] # (7000, 50, 1), (7000, 1)
X_valid, y_valid = series[7000:9000, :n_steps],
                   series[7000:9000, -1]
X_test, y_test = series[9000:, :n_steps],
                 series[9000:, -1]
```

4.1 Implementing a Simple RNN

```
# Sequential model of one neuron
```

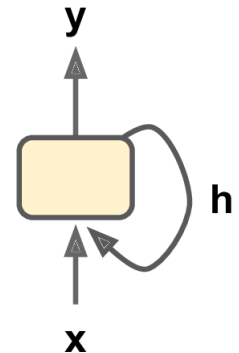
```
model = keras.models.Sequential([  
    keras.layers.SimpleRNN(1, input_shape=[None, 1])
```

```
])
```

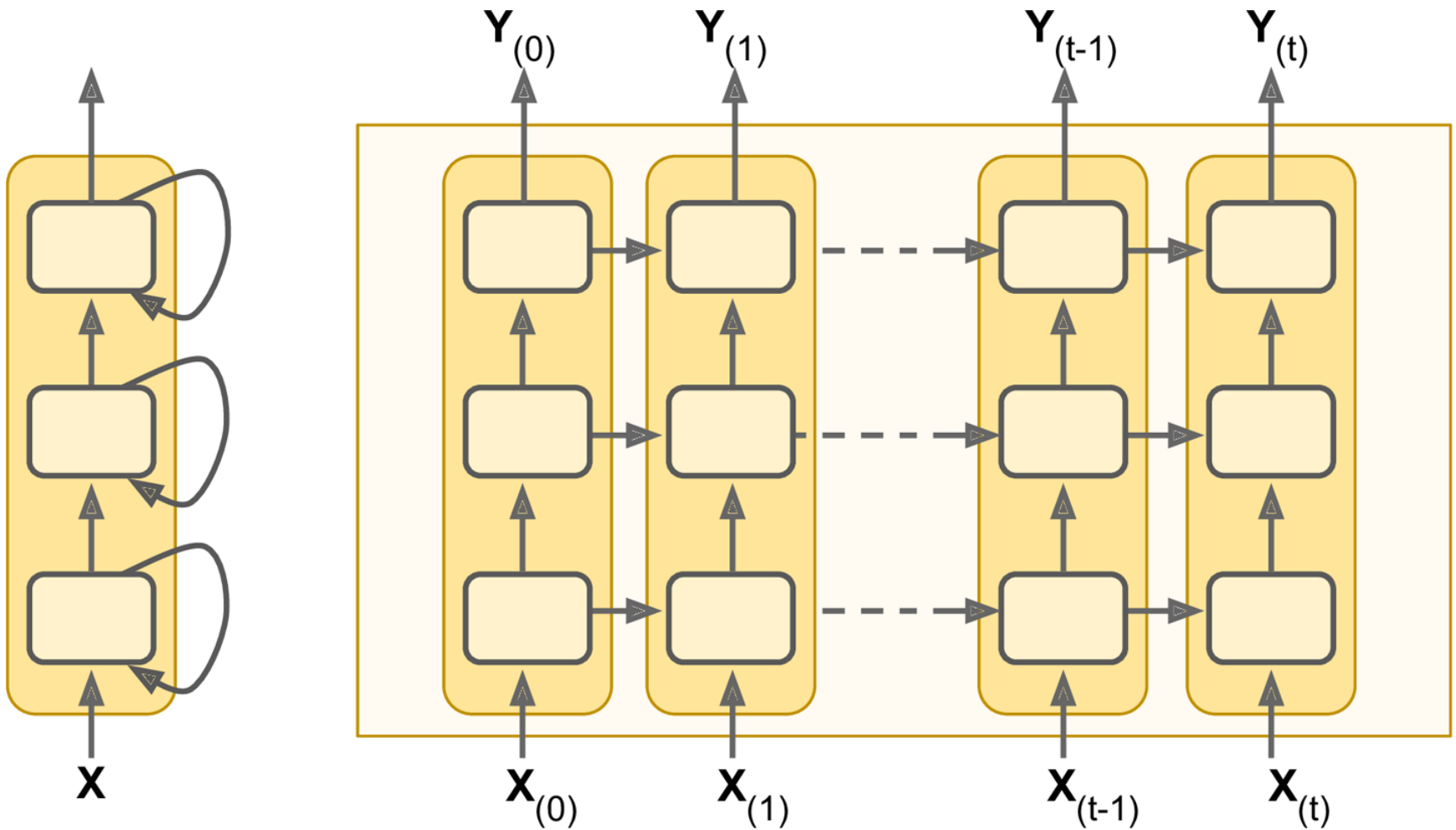
Uses tanh
activation $h_t = y_t$

```
optimizer = keras.optimizers.Adam(lr=0.005)  
model.compile(loss="mse", optimizer=optimizer)  
history = model.fit(X_train, y_train, epochs=20,  
                    validation_data=(X_valid, y_valid))
```

```
model.evaluate(X_valid, y_valid) # MSE = 0.011  
# Dense achieves 0.004
```



4.2 Deep RNNs



4.2 Deep RNNs

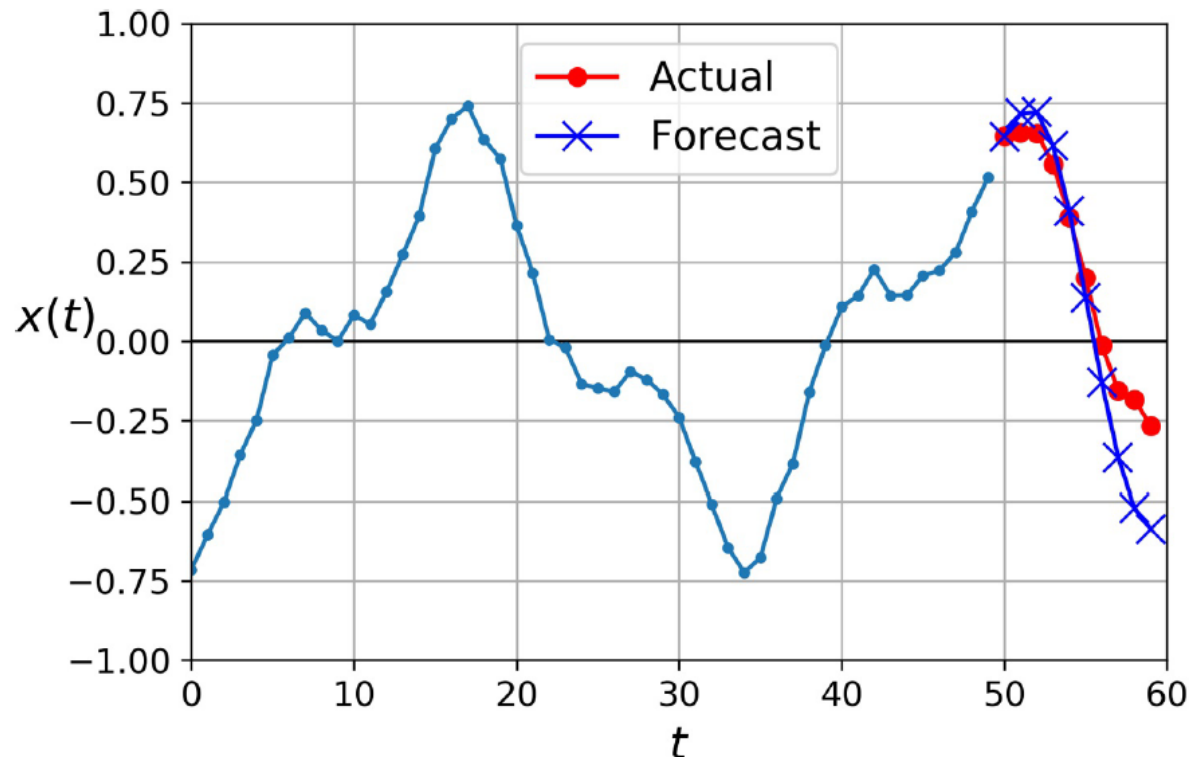
Sequential model of two hidden RNN layers

```
model = keras.models.Sequential([
    keras.layers.SimpleRNN(20,
        return_sequences=True, # output all steps
        input_shape=[None, 1]),
    keras.layers.SimpleRNN(20),
    keras.layers.Dense(1)
])
```

MSE = 0.0026

4.3 Forecasting Several Time Steps Ahead

- Can train an RNN to predict all **N next** values at once (sequence-to-vector model).
- The output layer should have N neurons.



4.3 Forecasting Several Time Steps Ahead

```
# Generate 10,000 time series with 10 steps ahead
series = generate_time_series(10000, n_steps + 10)

# Split them 7,000 : 2,000 : 1,000
X_train, y_train = series[:7000, :n_steps],
    series[:7000, -10, 0] # (7000, 50, 1), (7000,10)
X_valid, y_valid = series[7000:9000, :n_steps],
    series[7000:9000, -10, 0]
X_test, y_test = series[9000:, :n_steps],
    series[9000:, -10, 0]
```

4.3 Forecasting Several Time Steps Ahead

```
# Sequential model of two hidden RNN layers
```

```
model = keras.models.Sequential([  
    keras.layers.SimpleRNN(20,  
        return_sequences=True,  
        input_shape=[None, 1]),  
    keras.layers.SimpleRNN(20),  
    keras.layers.Dense(10)  
])
```

```
# MSE = 0.008
```

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5. Handling Long Sequences

- Training long sequences has two major challenges:
 - Unstable gradients
 - Forgetting the first inputs in the sequence
- For the **unstable gradients**:
 - **Does not help**: ReLU activation, batch normalization
 - **Helps**: good parameter initialization, faster optimizers, dropout

```
model = Sequential()  
model.add(layers.SimpleRNN(20, dropout=0.2,  
                           recurrent_dropout=0.2, input_shape=[None, 1]))  
model.add(layers.Dense(1))
```

To fight overfitting and
unstable gradients

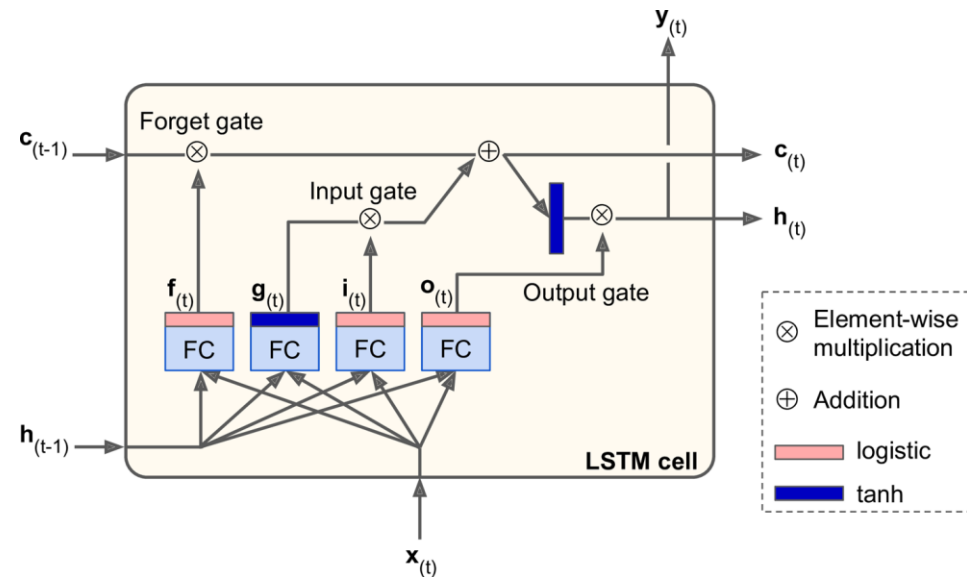


5. Handling Long Sequences

- To solve the **short-term memory problem**, use
 - **LSTM cell**
 - **GRU cell**
- These cells can be used in place of SimpleRNN

5.1 LSTM Cell

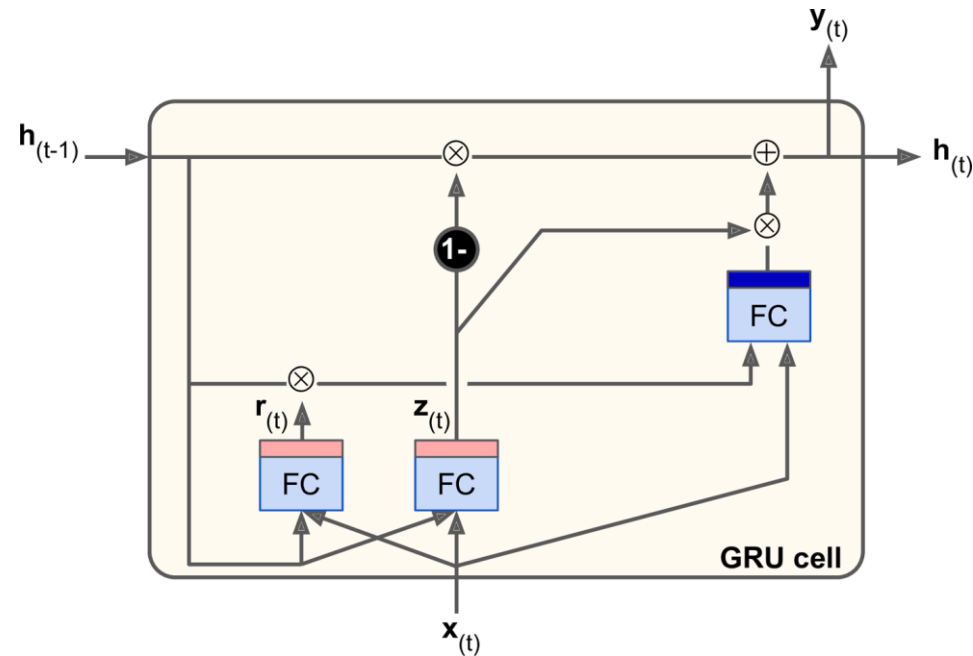
- The **Long Short-Term Memory** (LSTM) cell was proposed in 1997.
- Training converges faster and it **detects long-term dependencies** in the data.
- $h_{(t)}$ as the short-term state and $c_{(t)}$ as the long-term state.



```
model.add(LSTM(20))
```


5.2 GRU Cell

- The **Gated Recurrent Unit** (GRU) cell was proposed in 2014.
- **Simplified version** of the LSTM cell, performs just as well.
- A single gate controls the forget gate and the input gate.



```
model.add(GRU(20))
```

6. Exercises

From Chapter 15, solve exercises:

- 1 through 6

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